

Image Deformation using Radial Basis Function Interpolation

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Radial Basis Function

- A function $f: \mathbb{R}^d \rightarrow \mathbb{R}^d$ is known only at a set of discrete points $U := \{u_1, u_2, \dots, u_n\}$ and desired function values $V := \{v_1, v_2, \dots, v_n\}$, we can define

$$S_{f,U}(u) = \sum_{i=1}^n \alpha_i \phi(\|u - u_i\|) + \sum_{j=1}^m \beta_j p_j(u)$$

with the constraints

$$\sum_{i=1}^n \alpha_i p_j(u_i) = 0, \quad j = 1, 2, \dots, m$$

Here, $p_j(u) \in \Pi_r^d$ is the space of polynomial of total degree r in d spatial dimensions

Image Deformation

- As one field of computer graphics
- The deformation method of changing image to be wanted by user
 - Used in the field of computer animation, morphing and medical image
- To perform deformation the user selects some set of handle
 - Points, lines, or grids

Previous Deformation Techniques

- Mesh base method
 - T. Igarashi, T. Moscovich, and J. F. Hughes, "As-rigid-as-possible shape manipulation.", ACM Trans. Graph 2005, 24, 3, pp 1134-1141 (2005).
 - Y. Weng, W. Xu, Y. Wu, K. Zhou, B. Guo, "2D shape deformation using nonlinear least squares Optimization.", The visual computer, pp 653-660(2006).
- Approximation method
 - S. Schaefer, T. McPhail, J. Warren, "Image deformation using moving least squares.", Proceedings of ACM SIGGRAPH, pp. 533-540 (2006).
 - N. Arad, N. Dyn, D. Reisfeld, Y. Yeshurun, "Image warping by radial basis functions: Application to facial expressions", Computer Vision Graphics and Image Processing, p.p 161-172 (1994).

- Calculate the coefficients of $S_{f,U}(u)$ that are acquired to satisfy $(n+m) \times (n+m)$ system of linear equations. We may be written in matrix form as

$$\begin{pmatrix} A & P \\ P^T & 0 \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \begin{pmatrix} V \\ 0 \end{pmatrix}$$

- Unique solution is obtained in case of the inverse of matrix

$$\begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \begin{pmatrix} A & P \\ P^T & 0 \end{pmatrix}^{-1} \begin{pmatrix} V \\ 0 \end{pmatrix}$$

where

$$A = \begin{pmatrix} \phi(\|u_1 - u_1\|) & \phi(\|u_1 - u_2\|) & \dots & \phi(\|u_1 - u_n\|) \\ \phi(\|u_2 - u_1\|) & \phi(\|u_2 - u_2\|) & \dots & \phi(\|u_2 - u_n\|) \\ \vdots & \vdots & \ddots & \vdots \\ \phi(\|u_n - u_1\|) & \phi(\|u_n - u_2\|) & \dots & \phi(\|u_n - u_n\|) \end{pmatrix}, \quad P = \begin{pmatrix} p_1(u_1) & p_2(u_1) & \dots & p_m(u_1) \\ p_1(u_2) & p_2(u_2) & \dots & p_m(u_2) \\ \vdots & \vdots & \ddots & \vdots \\ p_m(u_n) & p_m(u_n) & \dots & p_m(u_n) \end{pmatrix}$$

Image deformation using RBF

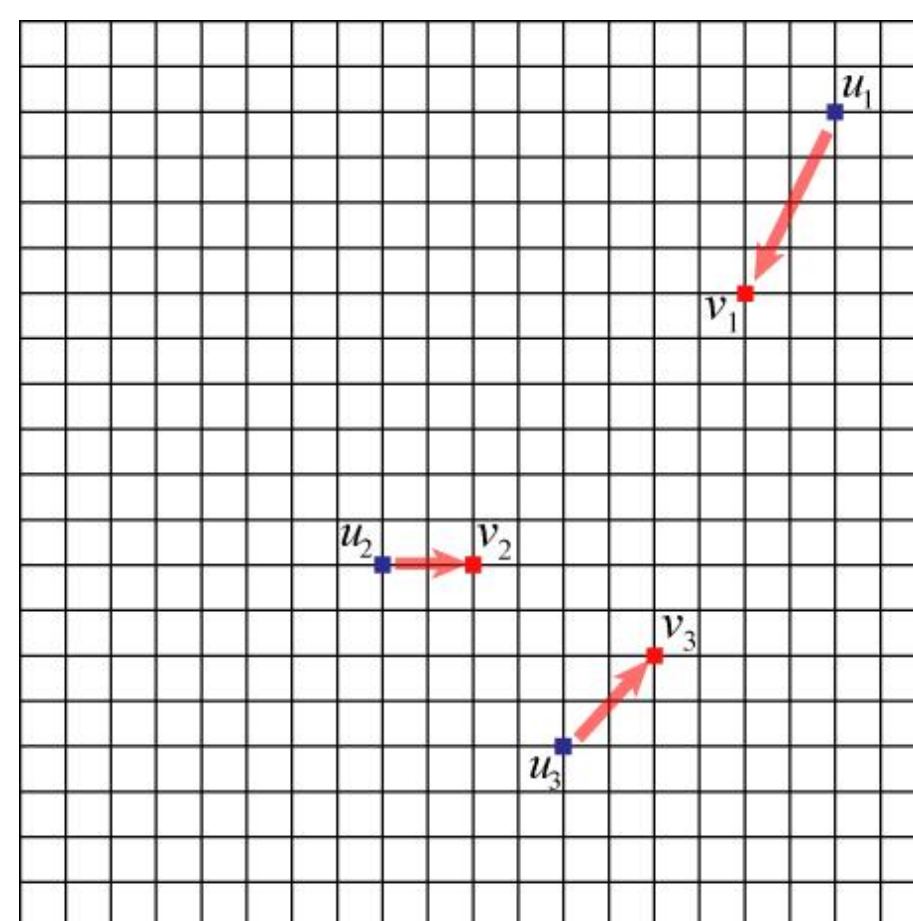
- Since constructing a deformed image from an original one is a mapping from \mathbb{R}^2 to \mathbb{R}^2 , we have given two sets of 2-dimensional data $U := \{u_1, u_2, \dots, u_n\}$ and deformed position $V := \{v_1, v_2, \dots, v_n\}$. We solve for the radial basis function interpolation $S_{f,U}(u)$, satisfying

$$S_{f,U}(u_i) = v_i - u_i, \quad i = 1, 2, \dots, n.$$

where $v_i - u_i$ is difference vector.

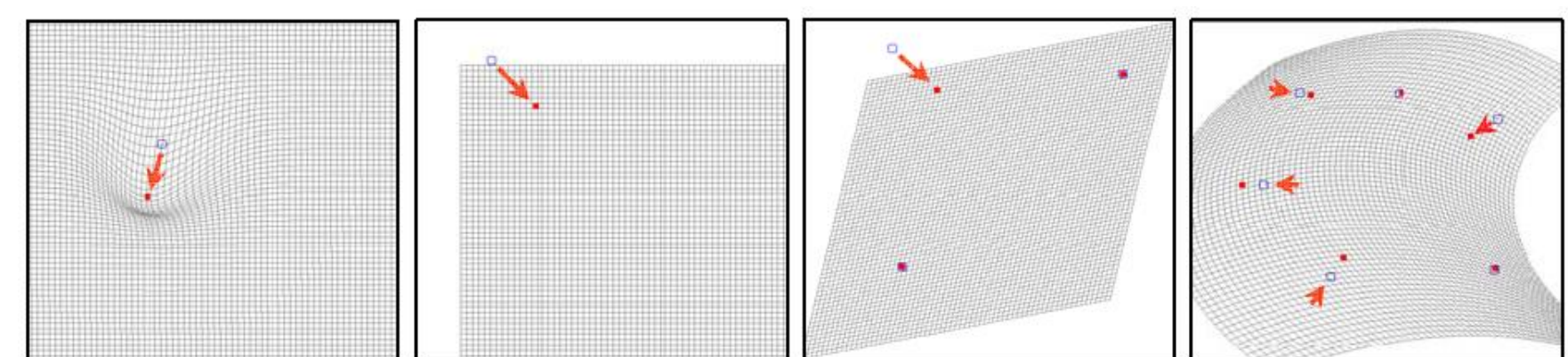
Finally, we obtain a deformed position v

$$v = u + S_{f,U}(u)$$



Experimental Result

- The deformation result according to polynomial degree



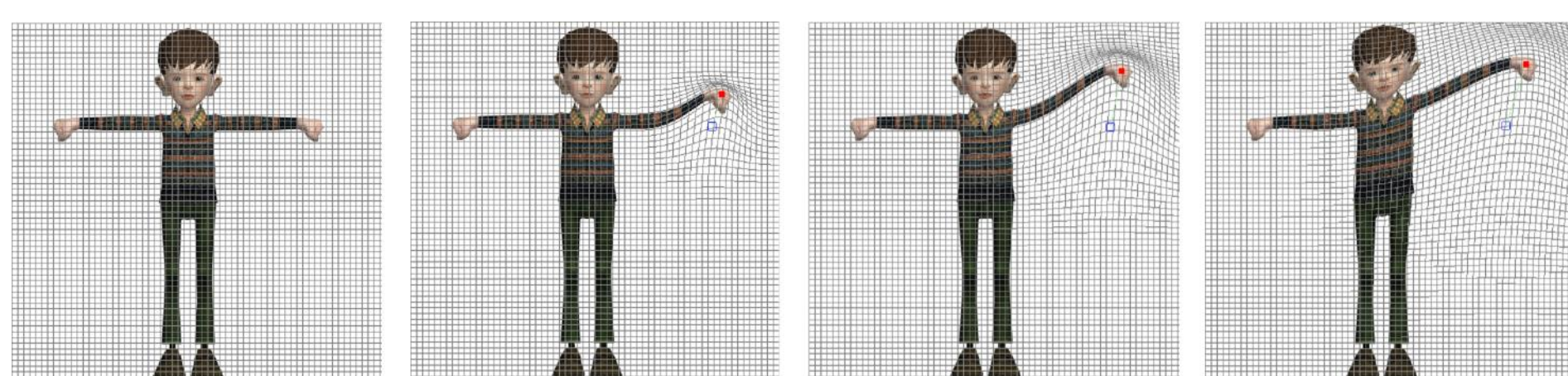
(a) without polynomial (b) with constant (c) with linear (d) with quadratic

- Test using Gaussian function $\phi(r) = e^{-r^2/c^2}$ and Wendland's function $\phi_{3,1}(r) = (1 - \frac{r}{c})^4 + (4\frac{r}{c} - 1)$ $c=10$



(a) Original image (b) Gaussin function (c) Wendland's function

- An illustration of RBF interpolation with different values of c



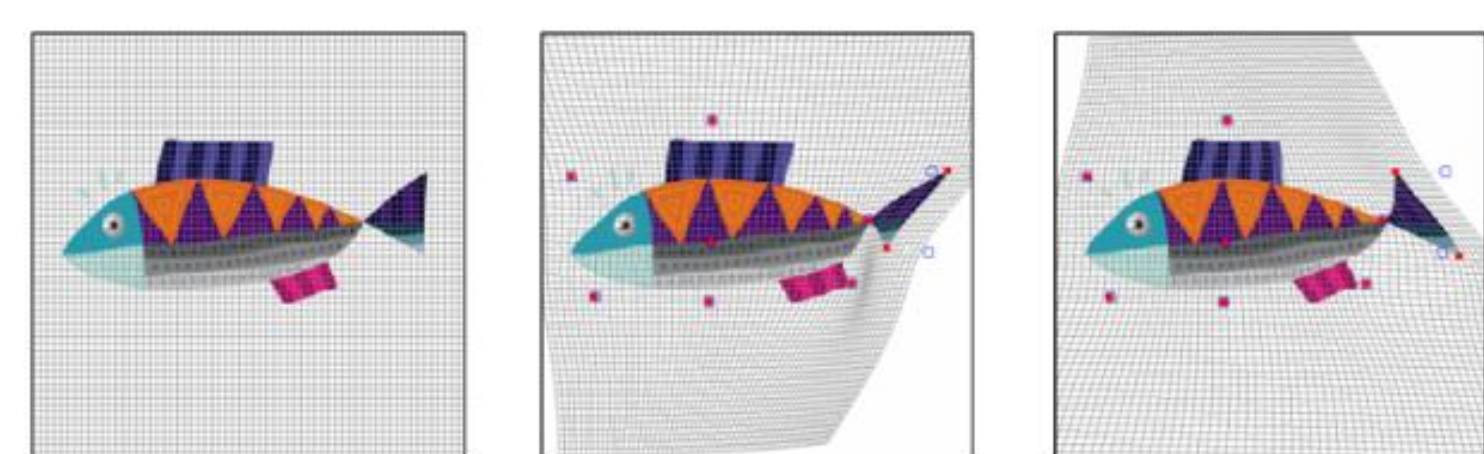
(a) Original image (b) c=5 (c) c=10 (d) c=15

- Comparison between our algorithm and [Schaefer et al.]



(a) Original image (b) Our algorithm (c) Schaefer et al.

- Deformation of a fish image



RBF with quadratic

Conclusion & Future work

- Our proposed method is faster by simple calculation and its result is better than the previous methods.
- The term of controlling polynomial degree has many possibilities for various application fields.
 - Especially, in field of animation.
- Further research will be extended to uses of other basis functions.
- line or curve segments instead of points as control attribute.